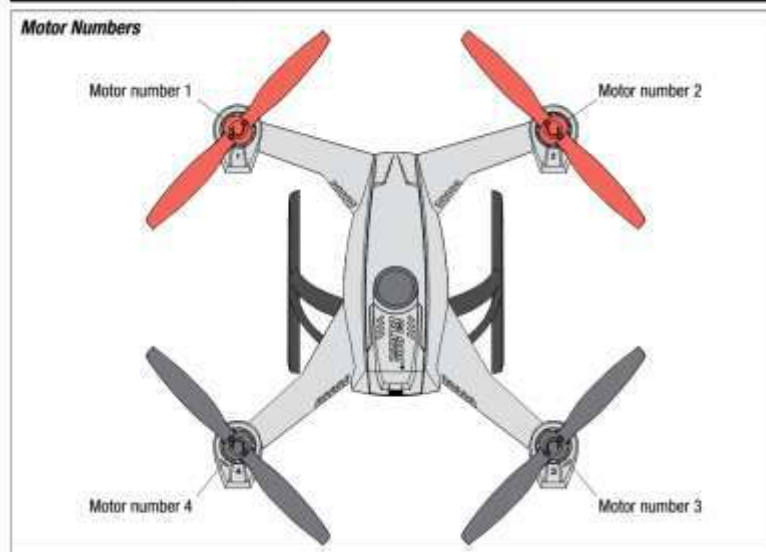


ESC and Motor Assignment Procedure



1. Begin with the transmitter off and connect a flight battery to the 350 QX2.
 2. Power on the quadcopter on a level surface and wait for the rapid blue flashing LED to indicate the aircraft has entered bind mode.
 3. With the throttle stick in the full throttle position, press/pull the bind button/switch and power on your transmitter. The quadcopter will acknowledge the assignment mode with a loud high, then low tone. If your transmitter is equipped with a high throttle warning at startup, it is necessary to disable this alarm prior to completing this step. After the replacement procedure is complete, re-activate the high throttle warning in your transmitter.
 4. The motor number and prop direction are molded in the top of the body. The motors will give an audible "beep" to indicate which motor to calibrate. When the motors beep 1 time, spin motor 1 by hand. The motor will respond with the same number of tones upon successful assignment.
 5. When the motors beep 2 times, spin motor 2 by hand.
 6. When the motors beep 3 times, spin motor 3 by hand.
 7. When the motors beep 4 times, spin motor 4 by hand.
- When the assignment is successful, the quadcopter enters emergency mode. Restart the quadcopter.